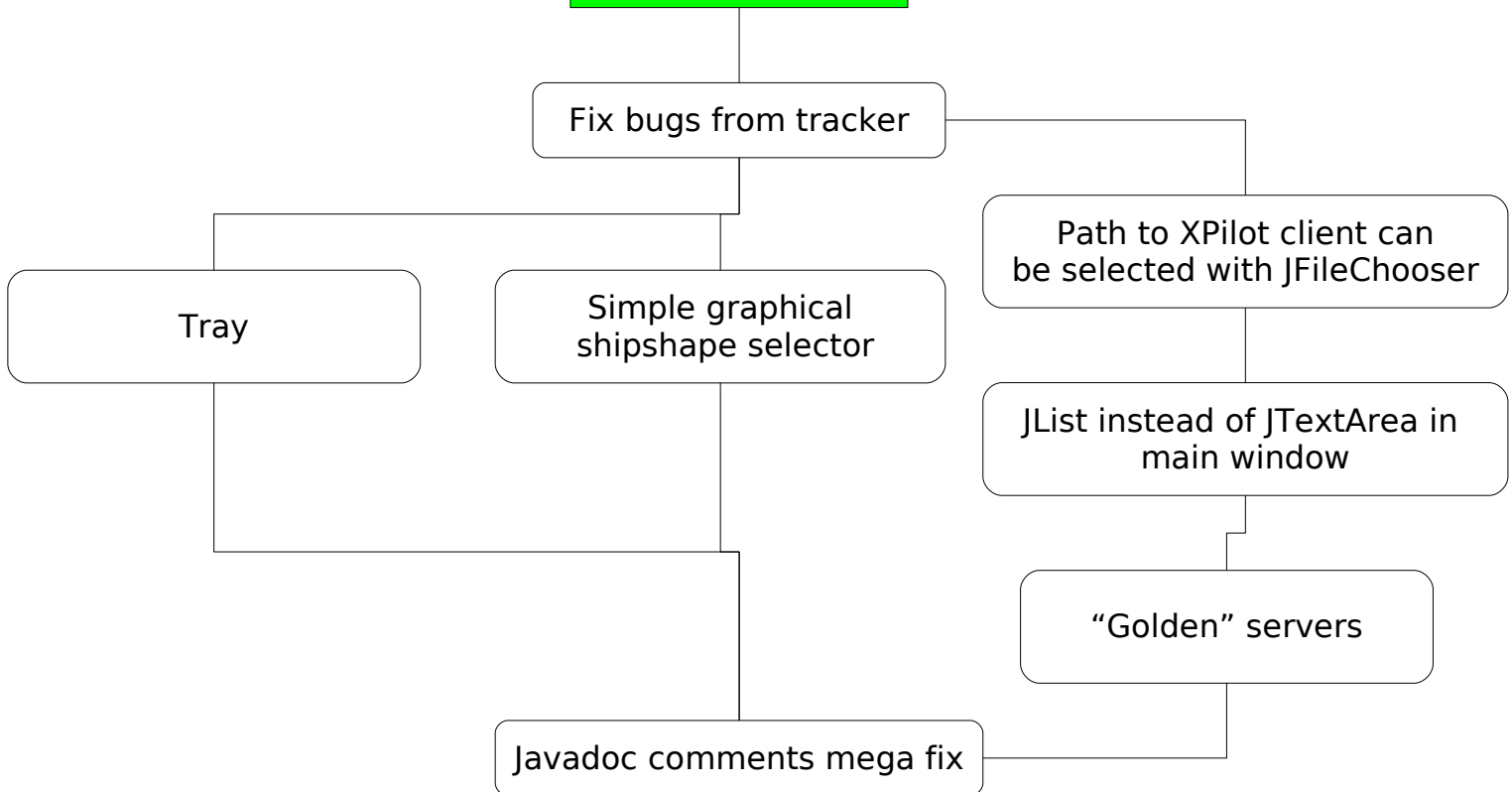
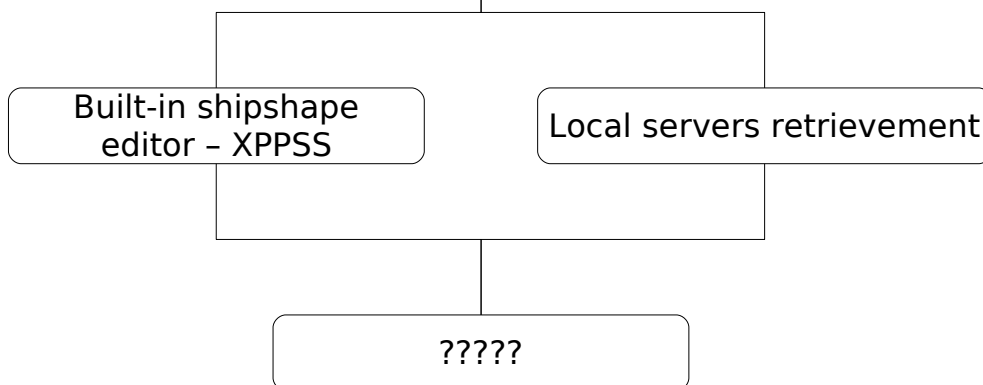



# Roadmap

0.2



0.3



 - done positions

 - goal